

A decision procedure for alternation-free modal μ -calculi

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Analysis of variants of graph rewriting systems
using decision procedures for satisfiability of temporal/modal logics

Previous work:

- Decision Procedure for two-way CTL [Hagiya et al 04]
 - Applied to analysis of one-dimensional cellular automata.
- Decision Procedure for alternation-free two-way μ -calculus [Tanabe et al 05]
 - Applied to analysis of XML transducers.

This research:

- Decision Procedure: (sublogics of) alternation-free μ + nominals + backward modalities + functional modalities.
(variants of enriched μ -calculus)
- Target: analysis of programs that manipulates pointers.

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Known results on satisfiability

$\mathcal{L}(\mu_{AF})$	EXPTIME-complete	[Emerson 90]
$\mathcal{L}(\mu_{AF}, \text{nom}, \text{back}, \text{func})$	Undecidable	[Bonatti, Peron 04]
$\mathcal{L}(\mu, \text{nom}, \text{back})$	EXPTIME-complete	[Sattler, Vardi 01]
$\mathcal{L}(\mu, \text{nom}, \text{func})$	EXPTIME-complete	[Bonatti et al 06]
$\mathcal{L}(\mu, \text{back}, \text{func})$	EXPTIME-complete	[Bonatti et al 06]
$\mathcal{L}(\text{nom}, \text{back}, \text{func})$	NEXPTIME-complete	[Tobies 00]

- μ : (full) μ -calculus
- μ_{AF} : alternation-free fragment of μ -calculus
- nom: nominals
- back: backward modalities
- func: functional modalities

Our decision procedure

Logic	Time Complexiy
$\mathcal{L}(\mu_{AF}, \text{nom}, \text{back})$	$2^{O(n^2 \log n)}$
$\mathcal{L}(\mu_{AF}, \text{nom}, \text{func})$	$2^{O(n^2 \log n)}$
$\mathcal{L}(\mu_{AF}, \text{back}, \text{func})$	$2^{O(n \log n)}$

- Existing procedures are automata-based.
 - Powerful: no restriction for alternation
 - Complex: $\geq 2^{O(n^4)}$ even for $\mathcal{L}(\mu)$.
- Ours is by simply enumerating possible nodes.
 - Only for alternation-free fragments.
 - Allows efficient implementation using BDDs.
 - Has successfully been applied to the target.

- 1 Background and Motivation
- 2 Syntax and Semantics
- 3 Decision Procedure
- 4 Application
- 5 Conclusion

PS $\ni p$	Propositional Symbols
Nom $\ni x$	Nominals
PV $\ni X$	Propositional Variables
FMS $\ni f$	Funcitonal Modality Symbols
GMS $\ni g$	General Modality Symbols
MS $\ni h ::= f \mid g$	Modality Symbols
Mod $\ni m ::= h \mid h^{-1}$	Modalities
Form $\ni \varphi$	Formulas
$::= p \mid x \mid X \mid \neg\varphi \mid \varphi \vee \varphi \mid \langle m \rangle \varphi \mid \mu X \varphi \mid @x \varphi$	

Kripke Structure $\mathcal{K} = (S, R, L)$

- S : Set of states
- $R : MS \rightarrow \mathcal{P}(S \times S)$
 - $R(h)$ is the transition relation for modality h .
 - $R(f)$ is a partial function if $f \in \text{FMS}$.
- $L : PS \cup \text{Nom} \rightarrow \mathcal{P}(S)$
 - $\mathcal{K}, s \models p \iff s \in \llbracket p \rrbracket \iff s \in L(p)$.
 - $L(x)$ is a singleton $\{L'(x)\}$ if $x \in \text{Nom}$.

$$R(m^{-1}) = R(m)^{-1}$$

Alternation-freeness

- Alternation-freeness is roughly equal to “ μ - ν nest-freeness”.
- Precisely, φ is **alternation-free** if it does *not* have patterns:

$$\varphi = \dots \mu X(\dots \nu Y(\dots X \dots) \dots) \dots$$

or

$$\varphi = \dots \nu X(\dots \mu Y(\dots X \dots) \dots) \dots$$

- $\mathcal{L}(\mu_{AF})$ allows much simpler decision procedure than $\mathcal{L}(\mu)$.
- It still has sufficient expressive power. Examples:
 - $\mu X(p \vee \langle m \rangle X)$: p is reachable by following m .
 - $\nu Y(q_1 \wedge ([m'](q_2 \wedge [m']Y)))$: q_1 and q_2 holds alternatively along m' -paths.
 - $\mu X(\nu Y(q_1 \wedge ([m'](q_2 \wedge [m']Y))) \vee \langle m \rangle X)$: their combination.
- CTL is a sublogic of $\mathcal{L}(\mu_{AF})$.

The **closure** $\text{cl}(\varphi_I)$ of a formula φ_I is approximately the set of its subformulas, except for fixed-point operators.

Example: $\varphi_I = \neg p \vee \mu X(p \vee \langle m \rangle X)$

$$\text{cl}(\varphi_I) = \{ \varphi_I, \\ \neg p, \mu X(p \vee \langle m \rangle X), \\ p, \quad p \vee \langle m \rangle \mu X(p \vee \langle m \rangle X), \\ \langle m \rangle \mu X(p \vee \langle m \rangle X) \}$$

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Decision procedure for $\mathcal{L}(\mu_{AF})$

Modification of the decision procedure for CTL [Emerson 90].
A tableau method. Each node is an element of $\mathcal{P}(\text{cl}(\varphi_I))$.

Outline

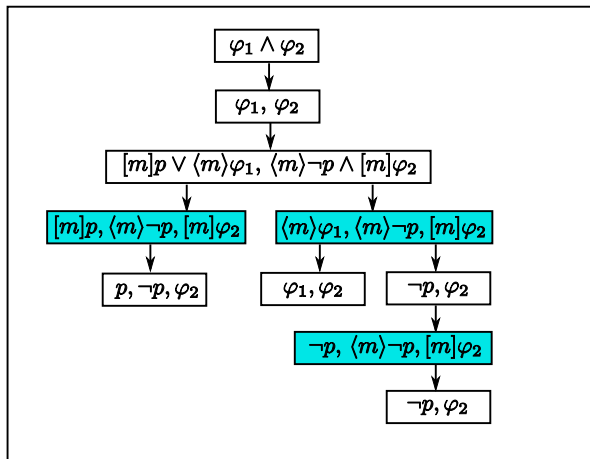
- 1 Start with initial node $n_0 = \{\varphi_I\}$.
- 2 Add nodes by decomposing existing nodes.
- 3 Remove all *inconsistent* nodes.
 - \neg -consistency, \diamond -consistency, and μ -consistency.
- 4 Repeat the previous step until all remaining nodes are consistent.

φ_I is satisfiable iff there remains a node that contains φ_I .

Decision procedure for $\mathcal{L}(\mu_{AF})$

$$\varphi_I = \varphi_1 \wedge \varphi_2, \quad \varphi_1 = \mu X([m]p \vee \langle m \rangle X), \quad \varphi_2 = \nu Y(\langle m \rangle \neg p \wedge [m]Y)$$

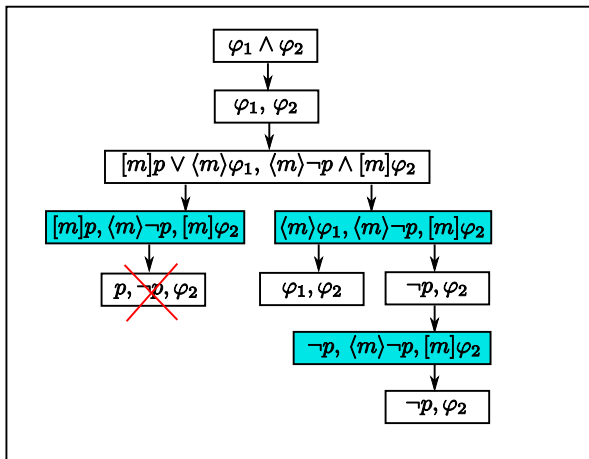
Adding nodes



Decision procedure for $\mathcal{L}(\mu_{AF})$

$$\varphi_I = \varphi_1 \wedge \varphi_2, \quad \varphi_1 = \mu X([m]p \vee \langle m \rangle X), \quad \varphi_2 = \nu Y(\langle m \rangle \neg p \wedge [m]Y)$$

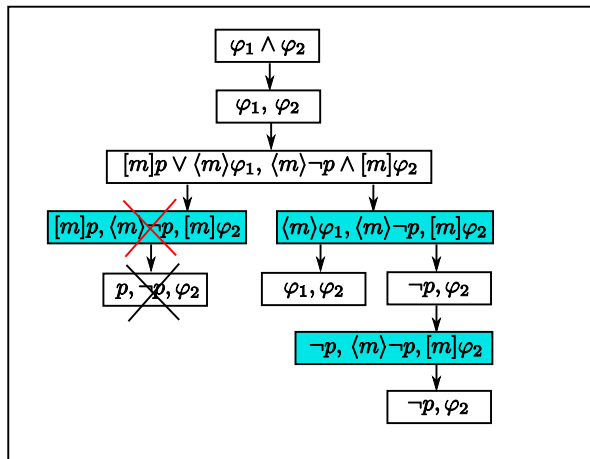
Checking \neg -consistency



Decision procedure for $\mathcal{L}(\mu_{AF})$

$$\varphi_I = \varphi_1 \wedge \varphi_2, \quad \varphi_1 = \mu X([m]p \vee \langle m \rangle X), \quad \varphi_2 = \nu Y(\langle m \rangle \neg p \wedge [m]Y)$$

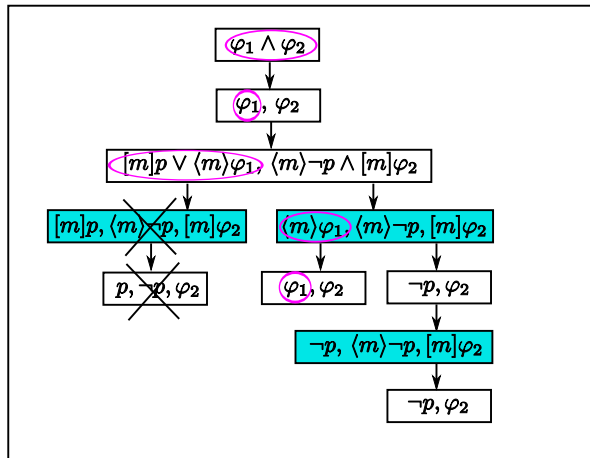
Checking \diamond -consistency



Decision procedure for $\mathcal{L}(\mu_{AF})$

$$\varphi_I = \varphi_1 \wedge \varphi_2, \quad \varphi_1 = \mu X([\![m]\!]p \vee \langle\langle m \rangle\rangle X), \quad \varphi_2 = \nu Y(\langle\langle m \rangle\rangle \neg p \wedge [\![m]\!]Y)$$

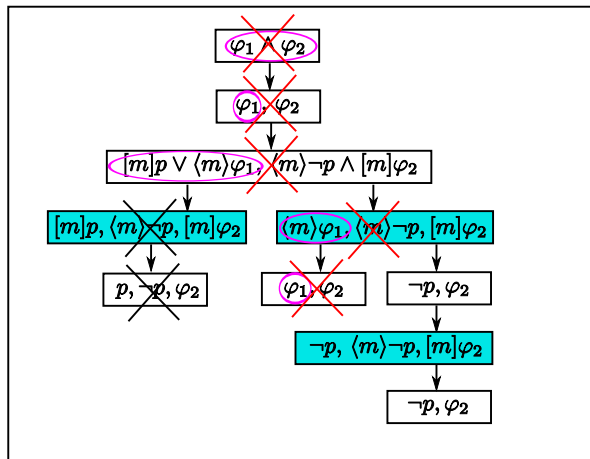
Checking μ -consistency – Remove μ -loops without witnesses



Decision procedure for $\mathcal{L}(\mu_{AF})$

$$\varphi_I = \varphi_1 \wedge \varphi_2, \quad \varphi_1 = \mu X([\![m]\!]p \vee \langle m \rangle X), \quad \varphi_2 = \nu Y(\langle m \rangle \neg p \wedge [\![m]\!]Y)$$

Checking μ -consistency – Remove μ -loops without witnesses



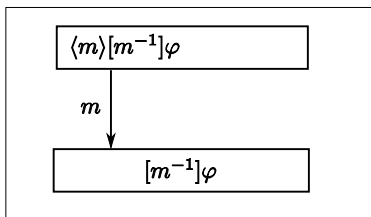
For a node n that contains only atomic formula, \diamond -formula and \square -formula:

- For every **formula** $\langle g \rangle \varphi$, where $g \in \text{GMS}$, add a node and put formulas φ and all ψ where $[g]\psi \in n$.
- For every **$f \in \text{FMS}$** , if there is $\langle f \rangle \varphi \in n$, add a node and put all formulas ψ where $\langle f \rangle \psi \in n$ or $[f]\psi \in n$.

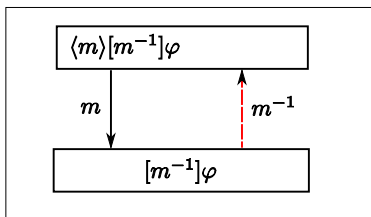
Backward Modality: Problem 1

$$\langle m \rangle [m^{-1}] \varphi$$

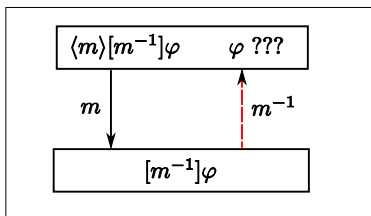
Backward Modality: Problem 1



Backward Modality: Problem 1



Backward Modality: Problem 1



Backward Modality: Solution to Problem 1

Outline of the procedure for given formula φ_I :

- 1 Start with initial node $n = \{\varphi_I\}$.
- 2 Add nodes by decomposing existing nodes.
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 - \neg -consistency, \diamond -consistency, and μ -consistency.
- 4 Repeat the previous step until all remaining nodes are consistent.

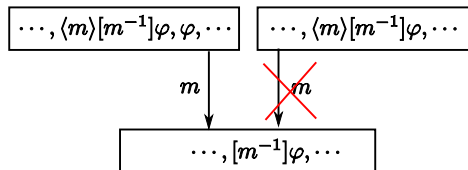
Backward Modality: Solution to Problem 1

Outline of the procedure for given formula φ_I :

- 1 Start with all possible nodes.
- 2 Remove all *inconsistent* nodes.
 - \neg -consistency, \diamond -consistency, and μ -consistency.
- 3 Repeat the previous step until all remaining nodes are consistent.

Backward Modality: Solution to Problem 1

- all possible nodes = all elements of $\mathcal{P}(\text{cl}(\varphi_I))$
- $(n, n') \in R(m) \iff$
 - $[m]\varphi \in n \implies \varphi \in n'$
 - $[m^{-1}]\varphi \in n' \implies \varphi \in n$



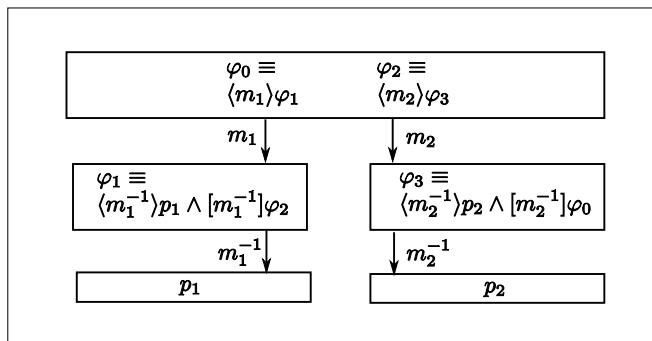
Backward Modality: Problem 2

$$\varphi_0 = \mu X(\langle m_1 \rangle(\langle m_1^{-1} \rangle p_1 \wedge [m_1^{-1}](\langle m_2 \rangle(\langle m_2^{-1} \rangle p_2 \wedge [m_2^{-1}](p_2 \vee X))))$$

$$\varphi_0 \equiv \langle m_1 \rangle \varphi_1, \varphi_1 = \langle m_1^{-1} \rangle p_1 \wedge [m_1^{-1}] \varphi_2$$

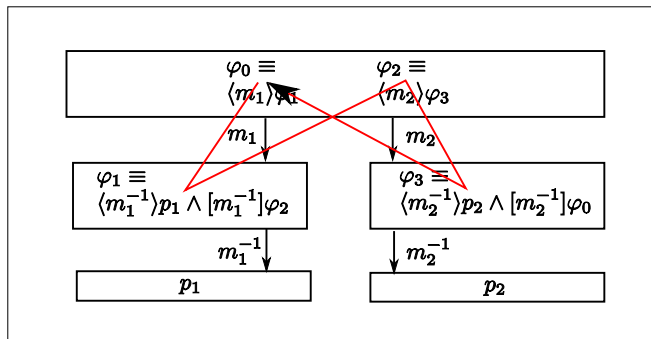
$$\varphi_2 = \langle m_2 \rangle \varphi_3, \varphi_3 = \langle m_2^{-1} \rangle p_2 \wedge [m_2^{-1}] \varphi_0$$

$$\varphi_I = \varphi_0 \wedge \varphi_2: \text{satisfiable formula}$$

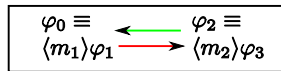
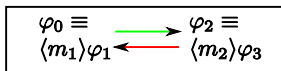


Backward Modality: Problem 2

- All nodes are μ -consistent.
- However, there is a μ -loop without witnesses.

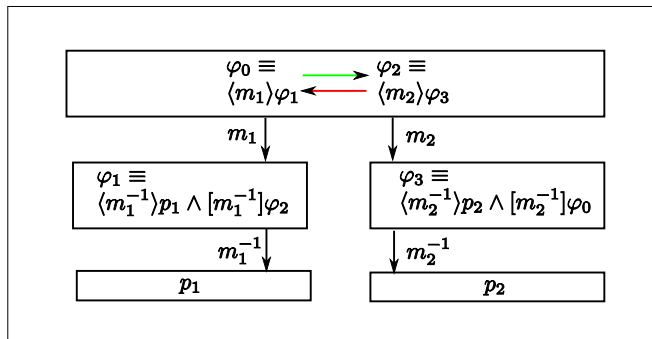


Backward Modality: Solution to Problem 2

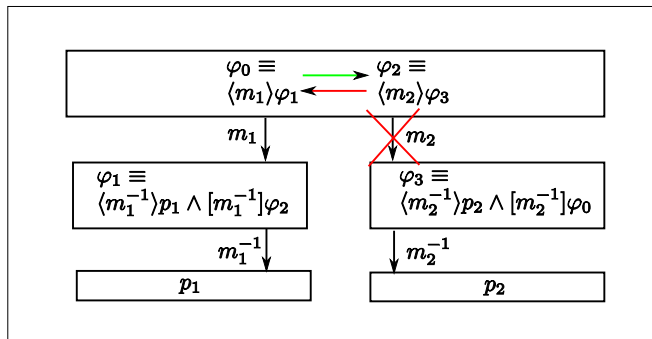


- Each node n is not just a member of $\mathcal{P}(\text{cl}(\varphi_1))$, but $n = (\Gamma, x)$, where
 - $\Gamma \subseteq \text{cl}(\varphi_1)$
 - x carries information on “expansion direction” (indicated by green and red arrows above) for μ -formulas

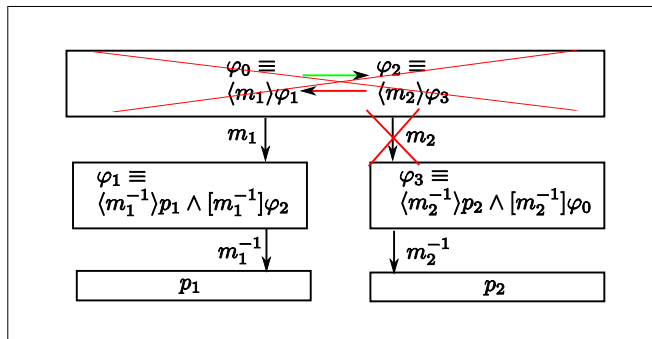
Backward Modality: Solution to Problem 2



Backward Modality: Solution to Problem 2



Backward Modality: Solution to Problem 2



Nominals: pseudo-nominal

If x is nominal,

- $\exists s \in S. \mathcal{K}, s \models x$
- $\mathcal{K}, s \models x \ \& \ \mathcal{K}.s' \models x \implies s = s'$.

(Propositional symbol) x is a **pseudo-nominal** in \mathcal{K} , if:

- $\exists s \in S. \mathcal{K}, s \models x$
- $\mathcal{K}, s \models x \ \& \ \mathcal{K}.s' \models x \implies \forall \psi \in \text{cl}(\varphi_I). \mathcal{K}, s \models \psi \iff \mathcal{K}, s' \models \psi$

Nominals: pseudo-nominal

$g : \text{Nom} \rightarrow \mathcal{P}(\text{cl}(\varphi_I))$ is a **naming function**, if

- $x \in g(x)$
- $x \in g(x') \implies g(x) = g(x')$

Used already in [Sattler, Vardi 01]

If x is a pseudo-nominal in \mathcal{K} ,

$$g : x \mapsto \{\varphi \in \text{cl}(\varphi_I) \mid L'(x) \models \varphi\}$$

is (well-defined and) a naming function.

Outline of the procedure for given formula φ_I :

- 1 Guess a naming function g .
- 2 Start with all possible nodes.
- 3 Remove all inconsistent nodes.
 - \neg -consistency, \diamond -consistency, and μ -consistency.
 - Node n such that $x \in n$ and $n \neq g(x)$.
- 4 Repeat the previous step until all remaining nodes are consistent.
- 5 If there is a node that contains φ_I , φ_I is satisfiable.
- 6 Otherwise, Go back to the beginning and try another g . Repeat this process until all g has been checked.

Nominals: duplicated node

- Each x is contained in one node.
- Not necessarily so in the resulting Kripke structure.
A node may relates to several status.

Nominals: avoiding duplication

Assume $\mathcal{K}, s \models \varphi$ and φ is a μ -formula. Let $\bar{y}(s, \varphi)$ be the number of nominals contained in the witness DAG D for (s, φ) .

- If (s', φ') is a successor of (s, φ) in D , then $\bar{y}(s', \varphi') \leq \bar{y}(s, \varphi)$.
- Furthermore, if $s' \models x$ for some $x \in \text{Nom}$, then $\bar{y}(s', \varphi') < \bar{y}(s, \varphi)$.

Now, each node n in the Tab is in the form of $n = (\Gamma, x, y)$. y carries the information of \bar{y} .

φ_I is satisfiable $\stackrel{?}{\iff}$ the procedure returns 'yes'

- \Rightarrow holds if φ_I is in $\mathcal{L}(\mu_{AF}, \text{nom}, \text{back}, \text{func})$
- \Leftarrow holds if φ_I is in $\mathcal{L}(\mu_{AF}, \text{back}, \text{func})$, $\mathcal{L}(\mu_{AF}, \text{nom}, \text{func})$, or $\mathcal{L}(\mu_{AF}, \text{nom}, \text{back})$,

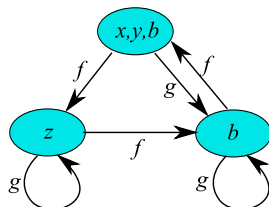
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Shape analysis

- Shape analysis: Analysis of programs that manipulates pointers.
- We regard the heap as a Kripke structure.

Example:

```
struct Node {  
  Node* f;  
  Node* g;  
  boolean b;  
}  
  
Node* x,y,z;
```



$PS = \{b\}$
boolean fields

$FMS = \{f, g\}$
pointer fields

$Nom = \{x, y, z\}$
pointer type variables

Properties of the heap

Properties of the heap is expressed by formulas.

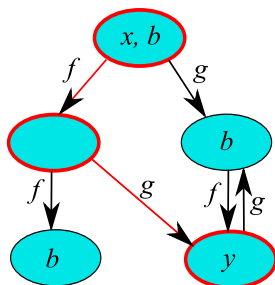
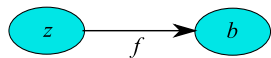
Example:

$@z \langle f \rangle b$

The f -successor of z satisfies b .

$@x \mu X (y \vee (b \wedge \langle f \rangle X) \vee (\neg b \wedge \langle g \rangle X))$

y is reachable from x by following pointer f or g , depending on whether b is satisfied or not.

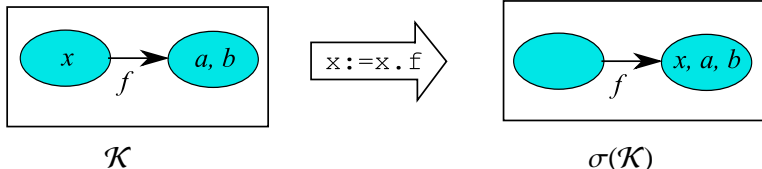


Weakest preconditions

For each “basic operation” σ and formula φ , we can define **formula** $\text{wp}(\sigma, \varphi)$ such that

$$\mathcal{K} \models \text{wp}(\sigma, \varphi) \iff \sigma(\mathcal{K}) \models \varphi$$

Example: $\sigma = \text{“}x := x.f\text{”}$, $\varphi = @x a \wedge b$



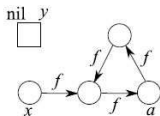
$$\text{wp}(\sigma, \varphi) = @x \langle f \rangle (a \wedge b)$$

Hoare-style proof example

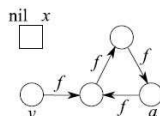
```

                                { @x EF(a) }
y := nil;                       { ψ }
while x != nil do               { ψ ∧ ¬@x nil }
  t := y;                       { (@t EU(¬x, a) ∨ @x EU(¬t, a))
                                ∧ @x ¬nil ∧ @t y }
  y := x;                       { φ1 = (@t EU(¬y, a) ∨ @y EU(¬t, a))
                                ∧ @y ¬nil ∧ @y x }
  x := y.f;                     { φ2 = (@t EU(¬y, a) ∨ @y EU(¬t, a))
                                ∧ @y ⟨f⟩x }
                                { φ3 = (@t EU(¬y, a) ∨ @y a
                                ∨ @x EU(¬y, a)) ∧ @y ⟨f⟩x }
  y.f := t                      { ψ }
od                               { ψ ∧ @x nil }   { @y EF(a) }

```



\mathcal{K}_1



\mathcal{K}_2

Judging Hoare triples

Hoare triple for “basic operation” can be verified using the weakest precondition and a decision procedure

If a decision procedure judges that

$$\varphi \rightarrow \text{wp}(\sigma, \psi) \text{ is valid,}$$

then hoare triple

$$\{\varphi\}\sigma\{\psi\} \text{ is correct.}$$

For this purpose, the decision procedure must be sound, but need not to be complete.

A system that helps the user to build Hoare-style proofs is implemented:

- Written in Java.
- Uses BDD (JavaBDD) for set operations.
- Pseudo-nominality.
- $\mathcal{L}(\mu_{AF}, \text{nom}, \text{func})$ with strongest postconditions.

Performance Examples

id	len	# cl	# nom	time (ms)
regr56	35	11	3	461
listRevNoLeakB	92	25	5	610
listRevSwapA	148	37	6	1199
dswPopC2	188	46	7	2615
dswPushA1	372	54	7	9469

Pentium 4 CPU 2.4GHz, 1GB mem, Windows XP.

Summary

- An implementable decision procedure for variants of enriched modal μ -calculus.
- Application to program analysis.

Future Work

- Implementation of the full decision procedure.
- Decision procedures for other variants, such as:
 - μ -GF, guarded fragments of the first order logic with fixed-point operators.
 - Some variants of multi-valued μ -calculus.

Thank you for your attention.

reg56 =

```
@ x1 nu Y1 ( !b1 & [n1] Y1 )
& @ x2 nu Y1 ( !b1 & [n1] Y1 )
& @ x1 mu X1 ( <n1> X1 | b1 )
& @ NULL <n1> NULL
```

dswPushA1 =

```
(( @ p ( p | ( <left> t & !p ) )
  & @ p <left> x
  & @ p mu XC ( ( @ t XC & p )
    | ( !p & <left> XC )
    | <right> XC
    | a
  )
  & ( !marked | p )
)
& @ p ( !marked | p )
& @ p !NULL
& @ p marked
& @ x mu X0 ( ( ( <right> X0 & swung )
  | ( !swung
    & ( ( @ t X0 & p )
      | ( !p & <left> X0 )
    )
  )
  & marked
  & !p
)
| NULL
)
& @ a ( ( ( <left> b & !p )
  | ( p & @ t b )
)
& <right> c
& ( !marked | p )
)
& @ a !NULL
& @ a !p
)
```

```
( ( @ p ( p | ( <left> t & !p ) )
  & @ p <left> x
  & @ p ( !marked | p )
  & @ p mu XC ( ( @ t XC & p )
    | ( !p & <left> XC )
    | <right> XC
    | a
  )
  & ( !marked | p )
)
& @ x mu X0 ( ( marked
  & ( ( !swung
    & ( ( @ t X0 & p )
      | ( !p & <left> X0 )
    )
  )
  & !p
  | ( ( swung | p ) & <right> X0 )
)
& !p
)
| NULL
)
& @ p !NULL
& @ p marked
& @ a ( ( ( <left> b & !p )
  | ( p & @ t b )
)
& <right> c
& ( !marked | p )
)
& @ a !p
& @ a !NULL
)
)
& @ NULL <left> NULL
& @ p !swung
& ( ( ( @ p nu XE ( ( !swung | [right] XE )
  & [right] nu XC ( ( [right] XC
    & [left] XC
    & !a
  )
)
)
)
)
```

```

| @ a t
| @ a ( [left] !b
| marked
| [right] !c
)
)
& ( @ a ( [left] !b
| marked
| [right] !c
)
)
| @ a !t
)
& ( @ t nu XC ( ( [right] XC
& [left] XC
& !a
)
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| marked
)
)
| @ a t
| @ a ( [left] !b
| marked
| [right] !c
)
)
)
| @ p nu X0 ( ( ( !swung | [right] X0 )
& ( swung | [left] X0 )
)
)
| !marked
)
& !NULL
)
)
| @ a NULL
)
& @ NULL <right> NULL

```